

 FLORIDA ATLANTIC UNIVERSITY	NEW COURSE PROPOSAL Graduate Programs		UGPC Approval _____ UFS Approval _____ SCNS Submittal _____ Confirmed _____ Banner Posted _____ Catalog _____
	Department Ocean & Mechanical Engineering College CECS <i>(To obtain a course number, contact erudolph@fau.edu)</i>		
Prefix EML Number 6317	<i>(L = Lab Course; C = Combined Lecture/Lab; add if appropriate)</i> Lab Code	Course Title Advanced Control Systems	
Credits <i>(Review Provost Memorandum)</i> 3	Grading <i>(Select One Option)</i> Regular <input checked="" type="radio"/> Sat/UnSat <input type="radio"/>	Course Description <i>(Syllabus must be attached; see Guidelines)</i> Control design applications via root locus and frequency based approaches will be explored theoretically and applied to laboratory systems. Nonlinear sliding mode control theory will be introduced and applied to a lab system. Each student will also explore an individual project based on control of a system.	
Effective Date <i>(TERM & YEAR)</i> Spring 2018	Prerequisites EML 4432 Dynamic Systems, or equivalent		Corequisites Registration Controls <i>(Major, College, Level)</i> Eng., Science, Math, Physics Graduate, Senior
Prerequisites, Corequisites and Registration Controls are enforced for all sections of course			
Minimum qualifications needed to teach course: Member of the FAU graduate faculty and has a terminal degree in the subject area (or a closely related field.)		List textbook information in syllabus or here Modern Control Engineering, 5th Edition, K. Ogata, Prentice Hall, 2010, ISBN-13:978-0136156734; Nonlinear Systems, 3rd Edition, Khalil Hassan, Prentice Hall, 2002, ISBN -13:978-0130673893	
Faculty Contact/Email/Phone Erik Engeberg, Ph.D. / eengeberg@fau.edu / x70530		List/Attach comments from departments affected by new course Computer & Electrical Engineering & Computer Science	

Approved by Department Chair <u>Janad Lelin</u> College Curriculum Chair <u>[Signature]</u> College Dean <u>[Signature]</u> UGPC Chair <u>[Signature]</u> Graduate College Dean <u>[Signature]</u> UFS President _____ Provost _____	Date <u>4/24/17</u> <u>4/24/17</u> <u>4/25/17</u> <u>4/25/17</u> <u>8/31/17</u> _____ _____
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Email this form and syllabus to UGPC@fau.edu one week before the UGPC meeting.

GRADUATE COLLEGE

APR 26 2017

Anastasia Calnick

From: Tsung-Chow Su
Sent: Thursday, April 20, 2017 11:28 AM
To: Zvi Roth
Cc: Anastasia Calnick
Subject: Re: Please provide support letter for Eric's course

Dear Zvi,

Thanks for your support.

Best

Joe

Sent from my iPhone

On Apr 20, 2017, at 11:17 AM, Zvi Roth <rothz@fau.edu> wrote:

Dear Dr. Su,

I strongly support Dr. Engeberg's proposed Control Systems course. None of the other control courses that we offer in the college has such hands on lab and project design activities for the students.

Regards,
Zvi

Dr. Zvi S. Roth
Professor
Department of Computer & Electrical Engineering & Computer Science
Florida Atlantic University
Engineering East Building, Room 519
777 Glades Road
Boca Raton, FL 33431
561-297-3471

From: Tsung-Chow Su
Sent: Thursday, April 20, 2017 10:48:39 AM
To: Zvi Roth
Subject: Please provide support letter for Eric's course

Dear Zvi,

Would you please support this course ?

Thanks

Best regards

1. Course title/number, number of credit hours	
EML 6317 Control Systems	3 credit hours
2. Course prerequisites, corequisites, and where the course fits in the program of study	
Prerequisites: Permission of Instructor; Dynamic Systems, or equivalent Mechanical Control Systems or equivalent	
3. Course logistics	
<i>Term:</i> Spring <i>Class hours:</i> 3 hours <i>Class location and time:</i> TBD	
4. Instructor contact information	
<i>Instructor's name</i> <i>Office address</i> <i>Office Hours</i> <i>Contact telephone number</i> <i>Email address</i>	Dr. Erik Engeberg Engineering West; Bldg. 36, Room 178 TBD 561-297-0530 eengeberg@fau.edu
5. TA contact information	
<i>TA's name</i> <i>Office address</i> <i>Office Hours</i> <i>Contact telephone number</i> <i>Email address</i>	N/A
6. Course description	
Control design applications via root locus and frequency based approaches will be explored theoretically and applied to laboratory systems. Nonlinear sliding mode control theory will be introduced and applied to a lab system. Each student will also explore an individual project based on control of a system.	
7. Course objectives/student learning outcomes/program outcomes	
<i>Course objectives</i>	This course introduces graduate students to an up-to-date account of the principles underlying the design, analysis, synthesis, and applications of control systems
<i>Student learning outcomes & relationship to ABET a-k objectives</i>	Covers objectives (a, e, g, k).
8. Course evaluation method	
<ul style="list-style-type: none"> • Labs 25% • Projects 40% • Midterm Exam 15% • Final Exam 20% 	

9. Course grading scale
Grading Scale: 90 and above: "A", 87-89: "A-", 83-86: "B+", 80-82: "B", 77-79 : "B-", 73-76: "C+", 70-72: "C", 67-69: "C-", 63-66: "D+", 60-62: "D", 51-59: "D-", 50 and below: "F."
10. Policy on makeup tests, late work, and incompletes
<i>Makeup tests</i> are given only if there is solid evidence of a medical or otherwise serious emergency that prevented the student of participating in the exam. Makeup exam should be administered and proctored by department personnel unless there are other pre-approved arrangements <i>Late work</i> is not acceptable. <i>Incomplete grades</i> are against the policy of the department. Unless there is solid evidence of medical or otherwise serious emergency situation incomplete grades will not be given.
11. Special course requirements
N/A
12. Classroom etiquette policy
University policy requires that in order to enhance and maintain a productive atmosphere for education, personal communication devices, such as cellular phones and laptops, are to be disabled in class sessions.
13. Disability policy statement
In compliance with the Americans with Disabilities Act (ADA), students who require special accommodations due to a disability to properly execute coursework must register with the Student Accessibility Services (SAS) located in Boca Raton campus, SU 133 (561) 297-3880 and follow all SAS procedures.
14. Honor code policy
Students at Florida Atlantic University are expected to maintain the highest ethical standards. Academic dishonesty is considered a serious breach of these ethical standards, because it interferes with the university mission to provide a high quality education in which no student enjoys unfair advantage over any other. Academic dishonesty is also destructive of the university community, which is grounded in a system of mutual trust and place high value on personal integrity and individual responsibility. Harsh penalties are associated with academic dishonesty. See University Regulation 4.001 at www.fau.edu/regulations/chapter4/4.001_Code_of_Academic_Integrity.pdf
15. Required texts/reading
<ul style="list-style-type: none"> • Modern Control Engineering, 5th Edition, K. Ogata, Prentice Hall, 2010; ISBN-13:978-0136156734 • Nonlinear Systems, Hassan Khalil, 3rd Edition, Prentice Hall, 2002; ISBN-13:978-0130673893
16. Supplementary/recommended readings
Control Systems Engineering, 7 th Edition, Norman S. Nise, Wiley

17. Course topical outline, including dates for exams/quizzes, papers, completion of reading

1. Week 1: Motor Modeling, Gear trains, Coulomb Friction
2. Week 2-3: Root locus-based controller design methods. Begin Lab 1.
3. Week 4: First project presentations by students.
4. Week 5-6: Frequency-based Controller Design Methods. Begin Lab 2.
5. Week 7-8: Introduction to state space equations Begin Lab 3. Midterm at end of week 8.
6. Week 8-11: Introduction to sliding mode control with applications.
7. Week 12-14: Control Systems Applications to modern systems.
8. Week 15: Final semester-long project presentations.
9. Week 16: Final exam

Note: the midterm will be during week 8 of the semester and the final exam will be during the regularly scheduled time at the end of the semester.

Lab 1 description: Model and control a double DC motor system working collaboratively to control the angle of a torsional spring load.

Lab 2 description: Experimentally ascertain the frequency response of the dual DC motor lab systems.

Lab 3 description: Estimate the transfer function of the DC motor lab system and use frequency based methods to design controllers to satisfy design criteria.

Semester Project: This will be a semester-long project that the student will explore based on control of a system. The project will consist of an initial presentation, a final presentation, and a final project report. The topic of the project will be mutually agreed upon by the Professor and student with the project deliverables defined prior to this initial presentation, which will occur during week 4 of the semester. The final presentation will occur during week 15 of class. The final report will be due at the time of the final exam.